Design And Implementation Soft-switching MPPT SEPIC Converter Using P&O Algorithm

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Abstract. This paper presents details of design and implementation of Maximum Power Point Tracking (MPPT) SEPIC Converter to maximize Photovoltaic (PV) power output. Perturb and observe (P & O) algorithm has been used as a tracking technique to determine MPPT. This algorithm are simple and efficient to determine the maximum power point (MPP). The soft-switching method will be added to the implementation of MPPT SEPIC Converter to reduce switching losses. The results show that the proposed MPPT method implementation can increase the output power of PV.

1 Introduction

In recent years, solar energy has gained great attention and popularity. This condition caused solar energy is considered the best solution for long-distance power applications that demand low voltage DC supplies that utilize alternative energy sources such as chargers for small electronic gadgets, laptops, uninterruptible power supply (UPS) and electric vehicles.

The solar energy sources conversion into electrical energy usually uses PV modules. Until now, PV is considered the best solution for remote area applications. PV has two major weakness, the power generated from PV is highly dependent on weather conditions and the conversion efficiency of PV systems is very low. However, the output characteristics of a non-linear PV module represent a unique operating point where there is maximum power generated in each irradiation. One common method to improve the efficiency of PV systems is develop MPPT controllers that continuously track MPP PV modules on all irradiation and temperature.

Many MPPT methods can be used to obtain optimal PV output power [1] - [6]. This adjusts to the complexity and needs of the system. Direct MPPT search methods such as Perturb and Observe (P&O), Incremental Conductance (INC) and Hill Climbing algorithms can be applied using spontaneous PV voltage (VPV) and PV current (IPV) values to generate control signals.

This paper focuses on the P&O algorithm because of its advantages, for example it can be implemented in analog and digital form, does not require periodic, efficient and easy to implement [2] [3] [8]. The P & O algorithm depend on the slope of the PV characteristic. In this paper, the SEPIC converter is used to validate the proposed P&O MPPT algorithm. Much research has

been done in this region that uses buck, boost, and buck boost converters.

Fig. 1. Topology of soft-switching MPPT SEPIC converter

Although the boost converter is more efficient than the SEPIC converter, but the SEPIC buck-boost property makes it more adaptable [9] - [11]. In this paper we also propose soft switching on SEPIC converters that have high efficiency to improve the overall efficiency of PV systems. A Soft Switching SEPIC converter is a converter that has a non-inverted buck-boost output and has a very high efficiency.

Figure 1 shows the topology of soft switching MPPT SEPIC converter. The voltage and current of the PV output will be sensed by the voltage sensor and current sensor. These currents and voltages are used to adjust the duty cycle switching converter and are used for the MPPT P & O algorithm. Furthermore, soft-switching DC-DC SEPIC converter as a circuit that serves to increase and decrease the voltage without changing the polarity of the resulting voltage. The output voltage sensor is used for monitoring the output voltage of the converter [12] - [14]. Then the proposed method will be compared with the conventional method so it can give an idea of the effect of using soft-switching MPPT SEPIC converter.

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2 Design System

In this study work has been used 6 PV modules with the capacity of each PV module is 135 WP. The PV module specifications are shown in Table 1.

Table 1. PV module specifications

Maximum Power (Pm)	135 WP
Open-circuit Voltage (Voc)	61,3 V
Short-circuit current (Isc)	3,41 A
Voltage at point of maximum power (Vmp)	47 V
Current at point of maximum power (Imp)	2,88 A
Modul efficiency	9 %
Number of Cell	45
Temperature coefficient-open-circuit voltage (α_{Voc})	-0,3
Temperature coefficient-short-circuit current (α_{Isc})	0,07
Temperature coefficient-power (α_{Pm})	-0,24

Based on the PV capacity has been used, then designed soft-switching MPPT SEPIC converter.

2.1. Design of SEPIC converter

In this work has been designed SEPIC converter with a capacity of 1000 Watt power. SEPIC converter can produce output voltage which can be higher or lower than input but without changing polarity. The inductor current and capacitor voltage limits are removed to investigate current and voltage fluctuations. The inductor current is assumed to work continuously on this analysis. The average inductor voltage is zero and the average capacitor current is zero for seady-state operation. *Kirchhoff's Voltage Law (KVL)* on circuit V_s , $L1$, $C1$ and $L2$

$$-V_s + V_{L1} + V_{C1} - V_{L2} = 0 \quad (1)$$

If it follows the assumption of the average voltage of the inductor, then the voltage on the capacitor $C1$ is

$$V_{C1} = V_s \quad (2)$$

When the switch is closed, the diode will be off and the circuit is shown in Figure 2.b. The transverse voltage $L1$ for the DT interfal is

$$V_{L1} = V_s \quad (3)$$

When the switch is open, the diode will be on and the circuit is shown in figure 2.c. KVL on the outer path is

$$-V_s + V_{L1} + V_{C1} + V_o = 0 \quad (4)$$

The assumption of capacitor voltage $C1$ remains constant at the mean voltage V_s

$$V_{L1} = -V_o \quad (5)$$

Fig. 2. (a) SEPIC circuit; (b) SEPIC circuit when switch is closed and diode off; (c) SEPIC circuit when switch open and diode on

For intervals $(1 - D) T$. Since the average inductor voltage is zero for periodic operation (steady state operation), then the equation becomes,

$$(V_s(DT) - V_o(1 - D)T = 0 \quad (6)$$

Where D is the duty cycle ratio of the switch, ie

$$D = \frac{V_o}{V_o + V_s} \quad (7)$$

The result of this equation is similar to buck-boost converter, with the important difference that there is no reversal polarity between the input and output voltages. The ability to have a voltage output greater or less than input without reversal polarity makes this converter suitable for many applications. The average current inductor which is also the current source can be searched by the equation:

$$I_{L1} = I_s = \frac{V_o I_o}{V_s} = \frac{V_o^2}{V_s R} \quad (8)$$

The variation in i_{L1} when the closed switch can be searched from the equation,

$$V_{L1} = V_s = L1 \left(\frac{di_{L1}}{dt} \right) = L1 \left(\frac{\Delta i_{L1}}{\Delta t} \right) = L1 \left(\frac{\Delta i_{L1}}{DT} \right) \quad (9)$$

Where Δi_L is

$$\Delta I_{L1} = \frac{V_s DT}{L1} = \frac{V_s D}{L1.f} \quad (10)$$

The average current in each capacitor is zero, so the mean current in $L2$ is,

$$I_{L2} = I_o \quad (11)$$

The variation in i_{L2} is determined from the circuit when the switch is closed. Using Kirchhoff's law of KVL, CI , and $L2$ with the voltage CI assumed V_s is constant, giving

$$V_{L2} = V_{C1} = V_s = L2 \left(\frac{di_{L2}}{dt} \right) = L2 \left(\frac{\Delta i_{L2}}{\Delta t} \right) = L2 \left(\frac{\Delta i_{L2}}{DT} \right) \quad (12)$$

Where Δi_{L2} is,

$$\Delta I_{L2} = \frac{V_s DT}{L2} = \frac{V_s D}{L2.f} \quad (13)$$

The current waveform is shown in Figure 3. Kirchhoff KVL's Law is applied to the drawings. 3 c, assuming no ripple voltage on the capacitor, indicating that the voltage going through the switch when open is $V_s + V_o$. From Figure 3 b, the maximum reverse voltage of the diode bias when the diode off is also $V_s + V_o$.

The output part consisting of diodes, $C2$, and load resistors is the same as in boost converter, so the output of ripple voltage is,

$$\Delta V_o = \Delta V_{C2} = \frac{V_o D}{R.C2.f} \quad (14)$$

Then $C2$ is,

$$C2 = \frac{D}{R(\Delta V_o/V_o)f} \quad (15)$$

The voltage variation in CI is determined from the shape of the circuit with the closed switch. The current capacitor i_{C1} is the reciprocal of i_{L2} , which has previously been determined to have an average value of I_o . From the definition of capacitance and considering the magnitude of charge,

$$\Delta V_{C1} = \frac{\Delta Q_{C1}}{C} = \frac{I_o \Delta t}{C} = \frac{I_o DT}{C} \quad (16)$$

Change I_o with V_o/R ,

$$\Delta V_{C1} = \frac{V_o D}{R C1 f} \quad (17)$$

Then CI is,

$$C1 = \frac{D}{R(\Delta V_{C1}/V_o)f} \quad (18)$$

Fig. 3. Current of SEPIC converter. (a) $L1$; (b) $L2$; (c) $C1$; (d) $C2$; (e) switch; (f) diode

2.2 P&O MPPT

The Perturb and Observe (P&O) algorithm is one of the simplest and easy to implement for MPPT. The design of MPPT requires two parameters to determine the slope of the control input voltage (V_{in}) and control input current (I_{in})

$$P_{in}(n) = V_{in}(n) \times I_{in}(n) \quad (19)$$

From these two parameters obtained Power (P_{in}), and voltage (V_{in}), then compared with the previous data reading parameters that is $P_{in}(n-1)$ & $V_{in}(n-1)$.

The result of comparison is obtained ΔP and ΔV

$$\Delta V = V_{in}(n) - V_{in}(n-1) \quad (20)$$

$$\Delta P = P_{in}(n) - P_{in}(n-1) \quad (21)$$

And the result of division ΔP and ΔV will be called slope.

$$Slope = \frac{\Delta P}{\Delta V} \quad (22)$$

As in Figure 4, there are 3 types of points that are in 3 positions. To the left of the $dP/dV > 0$ peak, the curve $dP/dV = 0$ and to the right of the peak $dP/dV < 0$. On the left side of the MPP the power changes to the voltage change $dP/dV > 0$, while on the right, $dP/dV < 0$, it is known that perturbation is done to move the PV working voltage forward MPP control. If dP/dV , then the work point change directs PV away from MPP. Then the P&O algorithm reverse the disturbance direction.

Fig. 4. Different $\Delta P / \Delta V$ positions on the PV curve

Flowchart of the P&O algorithm is shown in Figure 5. First of all measure or sensing voltage (V_K) and output current (I_K) PV. Then calculate the power with the multiplication of voltage and current of sensing result (P_K). Furthermore, compared to the current power (P_K) is greater than the previous power (P_{K-1}), if yes then compare the current voltage (V_K) is greater than the previous voltage (V_{K-1}), if yes then naiakn Vref by raising duty Cycle on the converter. Conversely if not, then lower the Vref by lowering the duty cycle. If the current power (PK) is not greater than the previous power (P_{K-1}), then compare the current voltage (V_K) is greater than the preceding voltage (V_{K-1}), if yes then naiakn Vref by raising the duty cycle on the converter. Conversely if not, then lower the Vref by lowering the duty cycle.

Fig. 5. Flowchart of the P & O algorithm

2.3 Soft-switching

Voltage and current switching do not switch to zero instantaneously at turn-on or turn-off. There is a time duration during switching transitions (ie turn-on and turn-off switching). Power losses during switching exist in overlapping or overlapping regions of current waves and switch voltages during turn-on or turn-off. Since the average power is energy divided by the period, then the higher the switching frequency causes higher switching losses. Sharp and sudden switching transitions are also sources of electromagnetic interference (EMI) noise that can affect the performance of converters and other surrounding electrical equipment. Figure 6 shows the current and voltage graphs of switch SI during the switching cycle. At the time of the driver pulse from SI

off then SI turn-off. SI takes time t_{off} to completely turn off. During this time, there is an overlap of the current wave and voltage, resulting in a turn-off loss represented by the area below the P_{off} graph. At t_1 , the driver pulses on and switch SI will turn-on. At this time, the SI switch takes t_{on} of time for turn on. During this time, there is an overlap of current wave and voltage from SI , so the turn on losses occur.

Fig. 6. Power loss during switching turn-on and turn-off due to overlap between switching currents (I_{sw}) and switching voltages (V_{ds})

The switching loss problem of the switching switching operation can be reduced by using soft-switching. The term soft-switching in power electronics refers to the various techniques in which switching transitions are made to be more gradual or not sudden. Switching losses decrease due to power dissipation when switching transitions take place there is no overlap between the voltage and current on the switching.

3 Experimental Result

System testing will be performed on each device to see the data characteristics generated by the equipment and to know, then to be tested as a whole with integrated.

3.1 PV Test

PV testing is performed to determine the characteristics of PV to sunlight that falls on the surface of PV. Testing of 810 WP PV characteristics is shown in figure 7.

Fig. 7. PV characteristic

3.2 DC-DC SEPIC ConverterTest

This test is aimed to know the function of SEPIC converter as DC-DC converter which is used to increase and decrease voltage. The SEPIC converter test uses a modified resistive load but with a fixed input voltage of

100V and the duty cycle is fixed at 60%. This test is up to a nominal power of 1000 W. Switching waveform shown in Figure 8 is the drain-source waveform MOSFET.

Fig. 8. Drain-Source Signal MOSFET duty cycle 60%

The SEPIC converter test data is shown in Table 2.

Table 2. SEPIC Converter Testing

SEPIC							
Duty cycle	Vin (V)	Iin (A)	Iout (A)	Vo prak (V)	Vo teori (V)	Error (%)	Effisiensi (%)
60%	100	10	5	160	150	6,67	80,0
	100	8	4,2	153	150	3,33	80,33
	100	5	3	138	150	8	82,8
	100	4,8	2,8	148	150	1,3333	86,33
	100	3,5	2	162	150	8	92,57
	100	2,6	1,4	149	150	0,6667	80,23

From the test results seen the efficiency has been meet the design of the converter is 80% and the error voltage is not large ie error maximum 8%. After performing converter testing, it is expected that the converter is able to work well when integrated with PV fluctuate to find the maximum power of PV.

3.3 Integration Test

At the integration testing stage, the entire system is unified. Maximum Power Point Tracking Testing is integrated with SEPIC Converter as well as previously designed voltage and current sensors. The effect of MPPT P & O on finding the maximum or peak power value of PV 810 WP, testing open loop and close loop. The test is carried out with resistive load at nominal power. In the first test of open loop testing or non-controlled testing, the duty cycle of the SEPIC converter is maintained in all test conditions. While in the second test that is close loop testing or controlled testing, the duty cycle of SEPIC converter varies according to PV peak power condition in all test conditions.

From these tests, there will be differences in PV power output between controlled by soft-switching MPPT-SEPIC P & O and without control. Table 3 and 4 show power output between controlled by soft-switching MPPT-SEPIC P & O and without control. Collecting data between controlled and without MPPT control is

done almost simultaneously at the same time and day. This is due to the PV characteristics that have rapid variable data changes, such as current values and PV voltages. This is to find the maximum power value when the solar panel is in a load state when using MPPT controls or not.

Table 3. Data Test Results system without MPPT control

Vin (V)	Iin (A)	Vo (V)	Io (A)	Po (W)	Pin (W)
144,9	1,4	145	0,9	130,5	202,86
153,1	1,4	153,5	0,9	138,15	214,34
146,7	1,4	147	1	147	205,38
156,4	1,4	156,1	0,9	140,49	218,96
150,1	1,4	159,3	0,92	146,556	210,14
153	1,4	159,8	0,92	147,016	214,2
156	1,4	158	0,92	145,36	218,4
154	1,4	160,7	0,92	147,844	215,6
155	1,4	158	0,92	145,36	217
151	1,4	156	0,91	141,96	211,4
150	1,4	156	0,92	143,52	210
150	1,4	154	0,9	138,6	210
141	1,4	143	0,87	124,41	197,4
117	1,5	120	0,82	98,4	175,5

Table 4. Data Test Results system with MPPT control

Vin (V)	Iin (A)	Vo (V)	Io (A)	Po (W)	Pin (W)
120	1,8	135	0,83	112,05	216
122	2,1	141	0,86	121,26	256,2
130	2,3	153,2	0,85	130,22	299
130	2,3	170	0,9	153	299
130	2,6	172	0,93	159,96	338
132	2,6	176	0,94	165,44	343,2
141	2,8	176	0,94	165,44	401,1
142	2,7	183	0,96	175,68	383,4

From the system test results, it can be compared that the MPPT tracking results can be better than tracking when the converter duty cycle is made fixed under all conditions. This proves the program has been properly running and can find the maximum power of PV. The amount of MPPT power increase can be proportionalized in Table 5 Since the power when the duty cycle fix is 40% is very far from the other power, then that compares only MPPT P & O power and 50% duty cycle fix power to see the percentage of MPPT P & O power increase. Figure 9 show graphic of comparation

between SEPIC converter with control and without control.

Fig. 9. comparison between SEPIC converter with control and without control.

Table 5. MPPT power increase

Time (+7GMT)	P without MPPT (W)	P with MPPT (W)	Power increase (%)
8.30	202,86	216	6,083333
9.00	214,34	256,2	16,3388
9.30	205,38	299	31,31104
10.00	218,96	299	26,76923
10.30	210,14	338	37,8284
11.00	214,2	343,2	37,58741
11.30	228,4	401,1	44,68085
12.00	215,6	383,4	43,7663
12.30	217	350	38
13.00	211,4	324,3	34,81344
13.30	210	300	30
14.00	210	234	10,25641
14.30	197,4	204	3,235294
15.00	175,5	180	2,5
Average power increase with MPPT			31,98

4 Conclusion

Soft-switching MPPT SEPIC converter using P & O algorithm can increase the output power of PV. Based on experimental results that have been done, about 31.98%. Although the method succeeded in tracking the power and able to raise the power to more than 30%, but this power value is still far from the maximum power of PV that has a maximum power of 810WP. Power that can be optimized using this method is only capable of a maximum of 401.1 W that is less than 50% of the maximum power of PV. There are many factors that influence, one of which is the physical state of PV is dirty, the existence of buildings that block the entry of light into the PV and the sensor is less precise in reading

the data. So, for the future will be done optimization on it.

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