



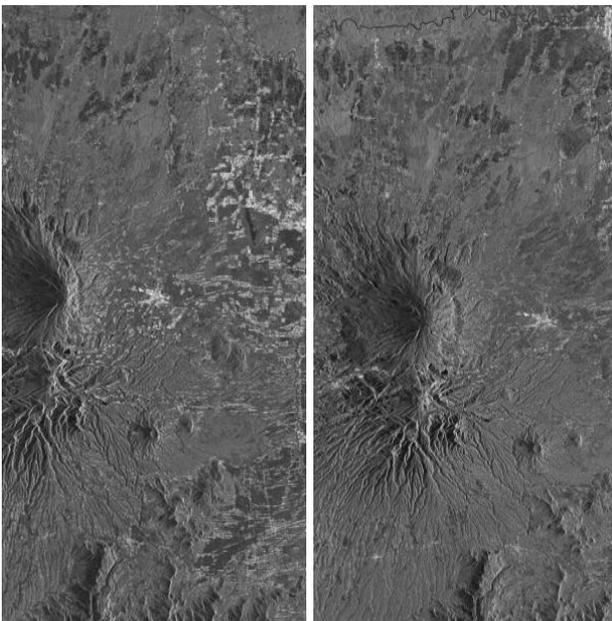
**Table 1.** Characteristic of TerraSAR-X images pairs.

	Image 1	Image 2
Sensor	TerraSAR-X	TerraSAR-X
Imaging Mode	StripMap	StripMap
Acquisition time	24/03/2018 22.22.10- 22.22.18	10/04/2018 22.13.39- 22.13.48
Product Type	SSC	SSC
Scene Centere Incidence Angle	28.765	47.653
Pass	Descending	Descending
Side Look	Right	Right
Polarization	HH	HH

## 2 Study Area and Processing

The study is carried out around Madiun City area, East Java. The characteristic of the surface relief of this area varies around agricultural lands, urban area, hills, and mountain. This elevation from this area ranges from 60 meters to 3265 meter while the maximum altitude is the peak of Lawu mountain.

Two TerraSAR-X images have been acquired on StripMap mode with HH polarization on Single-look Slant-range Complex (SSC). These images have same-side stereo pairs on descending orbits and have difference incidence angle of  $\sim 18.88^\circ$  with 17 days acquisition interval.

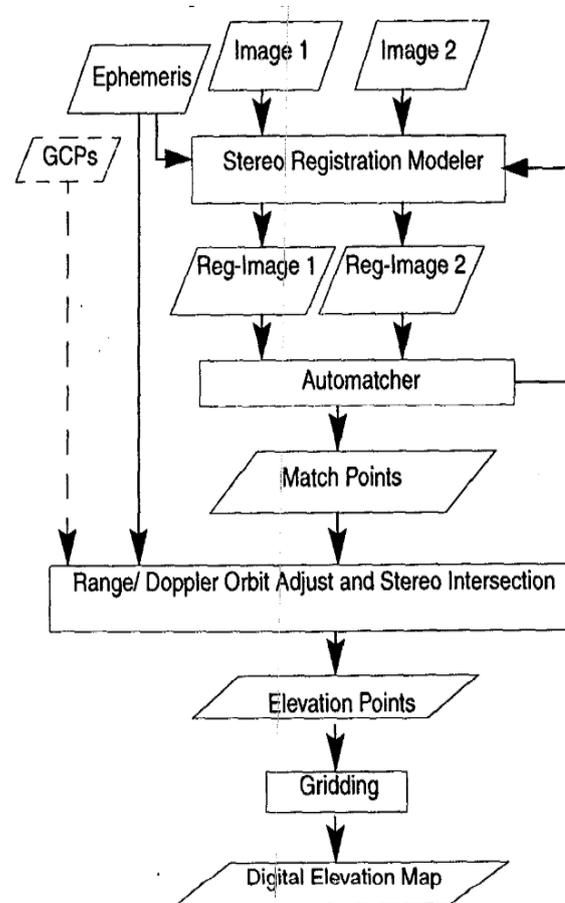


**Fig. 2.** Quick look of TerraSAR-X images pairs, taken at 24 March 2018 (left) and at 10 April 2018 (right).

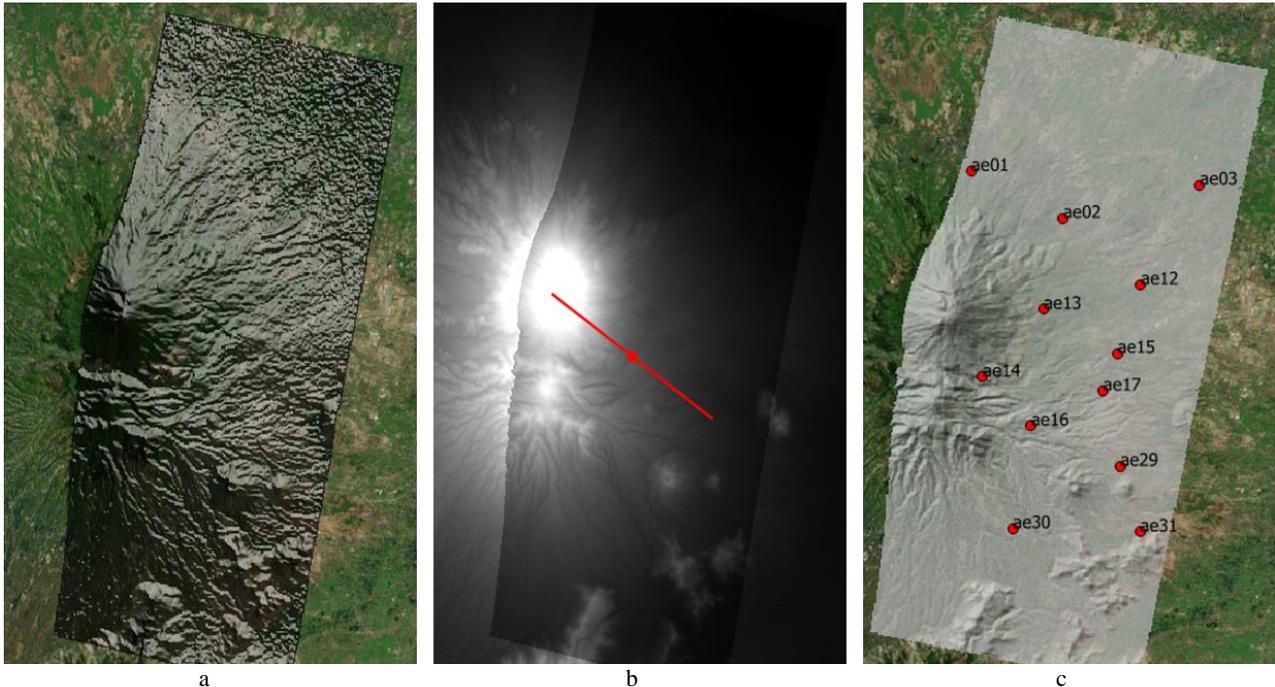
The process of stereo radargrammetry is carried out automatically in order to achieve high precision and avoid manual interaction of the user. This is due to SAR images which are heavily distorted both radiometrically and geometrically by the terrain, such as shadow provided by slopes which facing away from the sensor. Furthermore, SAR images also contains random speckle noise which make the reduce the resolution or filter with the reference DEM to cope with this speckle noise [8].

The main idea of the stereo matching process is by retrieving a shift in pixel on range direction which is proportional to the topographic height. The shift then estimated by the means of co-registration between the two images using amplitude (intensity) cross correlation. This whole process is performed in pyramidal way as the estimating of initial shift is on the multi-looked then refining it iteration by iteration to obtain finer estimate.

Later on, these shifts are converted to height and geocoded into a map projection. The difference with basic geocoding procedure is that we applied the two antennae simultaneously in Range-Doppler equations. From there, we can obtain the height of each pixel and its location (Easting, Northing) in a given cartographic and geodetic reference system.



**Fig. 3.** Stereo radargrammetry processing flow chart [9].



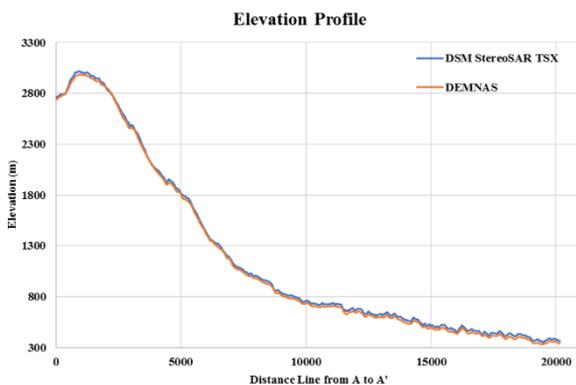
**Fig. 4.** (a) Result of DSM stereo radargrammetry TerraSAR-X, (b) Elevation profile line of DSM stereo and DEMNAS (c) Distribution points of GPS field observation.

### 3 Result and Discussion

The results of Digital Surface Model (DSM) created using stereo-radargrammetry in our area of study have high resolution with spatial pixel spacing around 5.57 meter. Furthermore, we carried out elevation accuracy measurement by comparing the elevation of the stereo DSM result to field elevation observation using GNSS GPS of Garmin Geo 7X with accuracy of 0.05 meter. We also evaluate the results of stereo DSM in our study to national digital elevation model (DEMNAS Indonesia) provided by Indonesia Geospatial Agency (BIG) by taking elevation profile of these two DEM. The DEMNAS is produced from DSM of IFSAR TerraSAR-X and ALOS-PALSAR with the accuracy improvement by processing addition of mass-points, spot-heights and break-line from topographic map using GMT-surface with tension 0.32[10].

The elevation profile between the DSM stereo radargrammetry TerraSAR-X and DEMNAS can be seen at Fig. 5 where its elevation follows the red line on Fig. 4b. Based on both figures, the generated DSM has similar elevation profile with DEMNAS.

The elevation accuracy measurement of the DSM stereo radargrammetry TerraSAR-X using GPS field observation can be seen at Table 2 with respective points shown at Fig. 4c. The result from this measurement, we obtain the absolute mean height error of the DSM stereo radargrammetry is 3.676 meter and root mean square error is 4.018 meter with the standard deviation of error is 1.695 meter.



**Fig. 5.** Elevation profile between stereo radargrammetry DSM and DEMNAS, x-axis follow the red line on Fig. 4a with the elevation on the y-axis.

**Table 2.** Elevation accuracy measurement of stereo radargrammetry DSM with GPS field observation.

Code No.	GPS Height (m)	DSM Height (m)	Accuracy (m)
ae01	427.327	427.822	0.495
ae17	396.7880	390.772	6.016
ae02	300.5590	298.384	2.175
ae03	100.9570	105.676	4.719
ae31	249.4020	253.655	4.253
ae30	537.7290	542.123	4.394
ae29	357.1200	355.111	2.009
ae16	877.6850	879.378	1.693
ae15	388.4250	393.343	4.918
ae12	259.3960	264.910	5.514
ae13	647.8580	651.992	4.134
ae14	1321.6930	1317.897	3.796

## 4 Conclusion

Digital Surface Model (DSM) generation using TerraSAR-X imagery in StripMap mode at Single-look Slant-range Complex (SSC) have been generated using stereo radargrammetry. The generated DSM have spatial resolution of 5.57 meter with elevation accuracy around ~4 meter. This proves that TerraSAR-X images capable of generating digital surface model (DSM) in stereo radargrammetry and show good result from it.

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