

Research on Magnetic Field Simulation of Cylindrical Linear Synchronous Motor

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Abstract. In order to obtain the influence of different structures and frequencies on the thrust of cylindrical permanent magnet linear synchronous motor, the transient simulation of magnetic field of cylindrical permanent magnet linear synchronous motor is carried out by using Ansoft software, and the correctness of the simulation is verified by experiments. Through simulation, the characteristics of the linear motor under different voltage frequency, air gap size, and permanent magnet width and its influence on the linear motor thrust are obtained.

1 Introduction

The cylindrical permanent magnet linear motor has the advantages of high thrust density, rapid dynamic response and reliable operation. It has been widely used in the field of high dynamic response servo and linear drive [1-3].

A large number of previous studies on cylindrical permanent magnet linear motor have been carried out. Through the combination of analytical method and finite element method, the theoretical and mathematical models of this kind of motor have been established, and verified by relevant experiments. Huang Kefeng and others explored the air gap magnetic density and waveform of cylindrical permanent magnet linear motor with each magnetizing structure, experimental results show that axial and Halbach magnetizing forms are characterized by large air-gap magnetic density, large range of variation and small effect of slotting [4]. For the further improvement of thrust density of cylindrical permanent magnet linear motor, Luo Ciyong proposed a special-shaped permanent magnet Halbach array and established a magnetic circuit analysis model, the permanent magnet angle is obtained when the thrust density is maximum [5]. Cui Junfan et al discussed the influence of different pole-slot coordination and primary core length on the performance of the motor, which improved the sine of the air-gap magnetic density waveform of the fractional cylindrical permanent magnet linear motor and improved the thrust performance [6]. By means of finite element method and analytical method, the optimal design of magnetic field, back potential, thrust force, armature reaction, eddy current loss and position reduction of cylindrical structure motor is carried out by wangjiabin and so on [7].

Although some achievements have been made in the research of cylindrical permanent magnet linear

synchronous motor, it is only based on theoretical research, lack of support of test data and test verification, and need to further improve the research to obtain accurate magnetic field characteristics. It lays a foundation for the research of cylindrical permanent magnet linear synchronous motor.

2 Simulation of Transient Magnetic Field in Cylindrical Linear Synchronous Motor

2.1 Establishment of numerical model of motor

The simulation model is drawn in the Cylindrical about Z coordinate plane by using the Transient module in the Ansoft according to the structural parameters of the actual cylindrical permanent magnet linear synchronous motor. This model includes Band for separating stationary parts from moving parts and Band in parts containing only moving parts, as shown in figure 1.

Primary motor 45 steel, nonlinear material; Copper winding is used for primary winding, resistivity is (1), relative permeability (2); Secondary selection of ZG20 materials, permanent magnet N-S alternately placed between the oblique extremely fast; relative permeability (2).

$$\rho = 2.17 \times 10^8 \Omega \cdot \text{m} \quad (1)$$

$$\mu_r = 1 \quad (2)$$

The outer air boundary is set as the balloon boundary condition, the secondary part of the model is the moving part, the upward motion is defined as the positive direction, the synchronous motion speed is 0.198 m/s, the moving area is 0~400 mm. The model of linear motor model is shown in figure 2. Set step size 0.001 s, stop time 0.5 s, a total of 500 steps.

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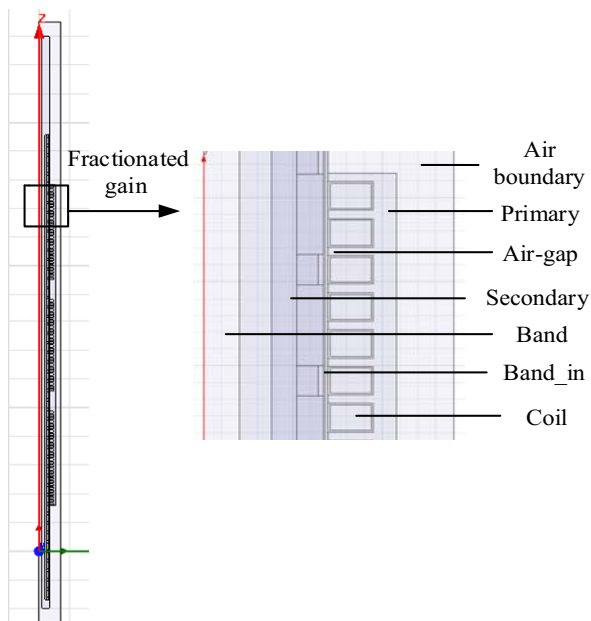


Fig. 1. Calculation model of cylindrical permanent magnet linear synchronous linear motor.

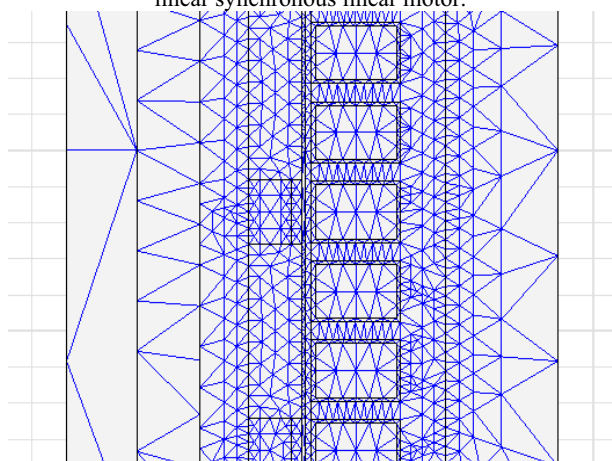
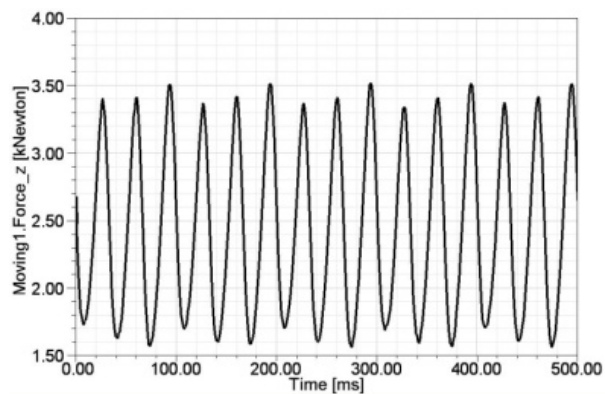


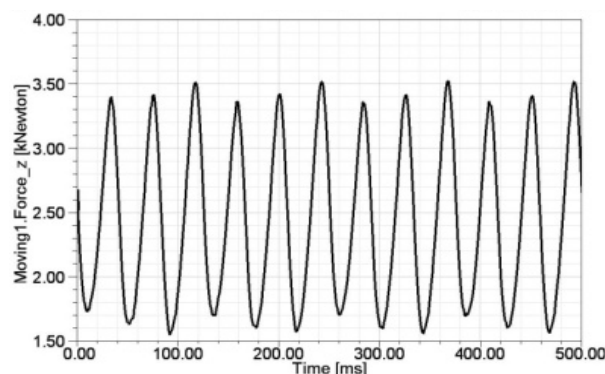
Fig. 2. Meshing diagram of linear motor model.

3 Simulation Model of Motor Transient Magnetic Field

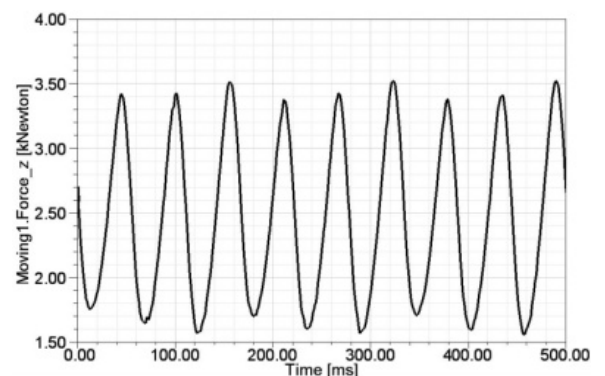
To verify the correctness of the simulation model, using Ansoft software to simulate 5 Hz、4Hz、3Hz respectively, the transient characteristics of magnetic field in the stable operation of cylindrical permanent magnet linear motor with three different frequencies are obtained. The thrust curve of cylindrical permanent magnet linear synchronous motor with different frequencies is shown in figure 3.



(A) 5Hz motor running thrust curve



(B) 4Hz motor running thrust curve



(C) 3Hz motor running thrust curve

Fig. 3. Linear motor thrust curve at three frequencies

The thrust value of linear motor at different frequencies can be obtained from figure 3(A)~(C). The comparison with the thrust value obtained from the test is shown in Table 1

Table 1 Comparison of simulated thrust value and experimental thrust at different frequencies

Frequency (Hz)	5	4	3
Simulated thrust value (N)	2525	2520	2550
Test thrust value (N)	2474.38	2573.38	2581.452
Deviation (%)	2.04	-2.08	-1.22

From Table 1, it can be seen that the error of using Ansoft software to simulate the thrust value of linear motor at different frequencies and the thrust value of

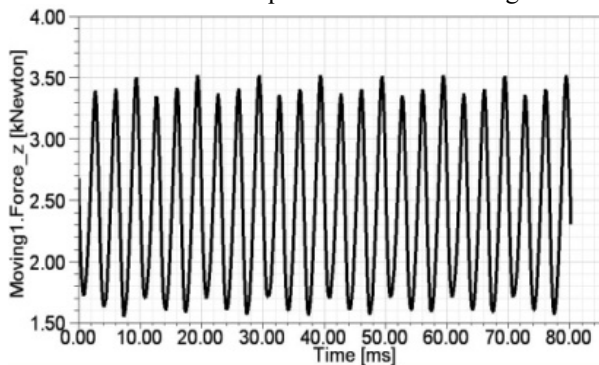
linear motor obtained by the test are 2.04%,-2.08%,-1.22%, respectively, and the error value is small, which proves the feasibility of the established transient simulation of linear motor magnetic field.

4 Analysis of electromagnetic field simulation results

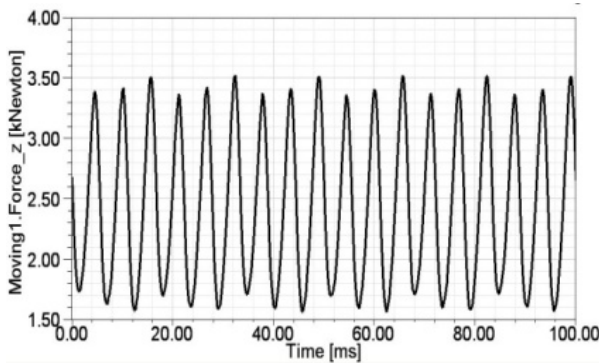
According to the simulation results, the transient characteristics of the linear motor under each parameter are analyzed and compared, and the influence of different parameters on the performance of the linear motor and its variation law are obtained.

(1)Effect of power frequency on thrust characteristics of linear motor

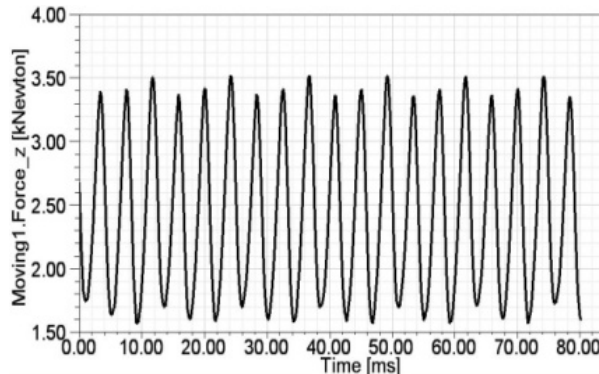
The three-phase AC frequency in the coil of cylindrical permanent magnet linear synchronous motor is 50 Hz、40Hz、30Hz, respectively to keep the amplitude of three-phase AC voltage fixed at 250 V. The electromagnetic thrust of cylindrical permanent magnet linear synchronous motor is simulated and simulated. The variation curve of secondary electromagnetic thrust with time at different frequencies is shown in figure 4.



(A) 50Hz



(B) 40Hz



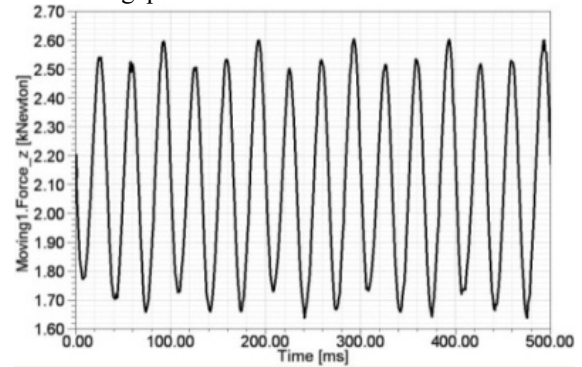
(C) 30Hz

Fig. 4. Motor thrust curves of three power supply frequencies varying with time

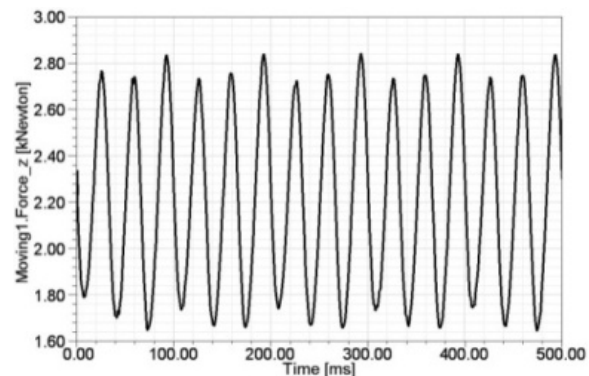
From the motor thrust curve at different power supply frequencies in figure 4, when the amplitude of the power supply voltage of the linear motor is fixed and only the frequency of the power supply is changed, the electromagnetic thrust of the linear motor is constant, but the frequency increases gradually.

(2)Effect of air gap on thrust characteristics of linear motor

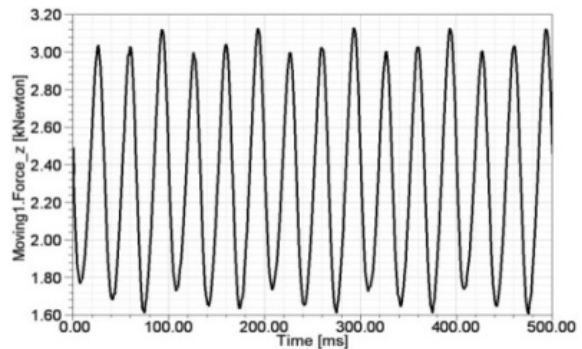
The air gap between the primary and secondary parts of the cylindrical permanent magnet linear motor is taken 2 mm、1.6mm、1.2mm, respectively mm、1.6mm、1.2mm, and the amplitude of the phase voltage of the power supply is 250 V, and the electromagnetic thrust of the linear motor is simulated when the frequency is 5. Figure 5 shows the thrust curve of different air gaps.



(A) 2mm



(B) 1.6mm



(C) 1.2mm

Fig. 5. Motor thrust curves of three types of air gaps with time

The thrust curve of linear motor with different primary permanent magnet width in Fig .6 shows that the secondary permanent magnet width is 27 mm, and the thrust of linear motor is 3900 N; Secondary permanent magnet width 21 mm, linear motor thrust 3350 N; Secondary permanent magnet 15 mm, linear motor thrust 3000 N. Therefore, it can be concluded that as the size of the secondary permanent magnet becomes smaller, the thrust value becomes smaller, and its value decreases from 3900 N at 27 mm width to 3000 N at 15 mm width.

5 Conclusion

(1) A simulation model of transient magnetic field characteristics of cylindrical permanent magnet linear motor is established by using Ansoft software, and the correctness of the simulation model is verified by test results;

(2) With the change of running frequency of linear motor pumping pump system, the thrust value is constant and the fluctuation amplitude of thrust value is constant, but with the increase of frequency, the frequency of thrust fluctuation increases, and the thrust value becomes larger with the decrease of air gap.

Acknowledgements

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